

Press-Information

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ASS presents new Robot Hand (EOAT) Plate

Robot Hand plate for extraction of falling items

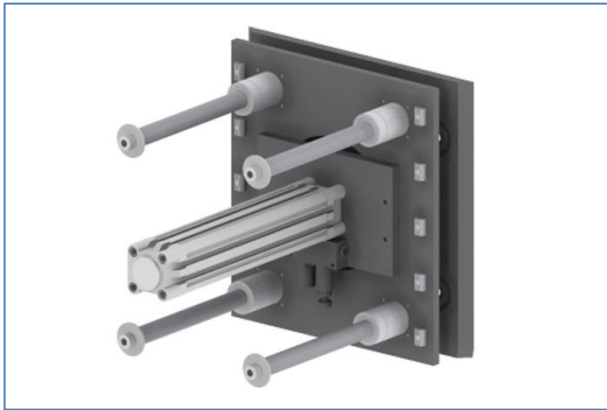
The new EOAT (Robot Hand) base plate with pneumatic cushioning GPG-P.

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The Robot Hand plate GPG-P is specially designed for the removal of parts falling off the mould. The pressure of regular GPGs is proportional to the stroke. The air cushioning of the new GPG-P is constant over the length of the whole stroke. The counter pressure is adjustable with the integrated control valve.

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Custom versions available on request.



Picture 1: EOAT (Robot Hand) Plate, „pneumatic“